

A glimpse at symplectic geometry and pseudo-holomorphic curves

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Three motivating questions

Question 1: dynamical systems

What can we say about periodic orbits of a mechanical system (e.g. double pendulum, the solar system)?

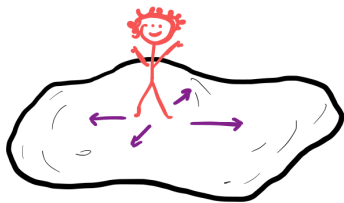
Question 2: symplectic fillings

When is a smooth manifold the boundary of a compact manifold?

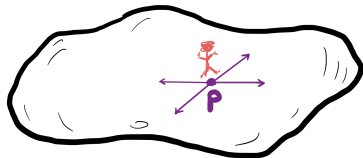
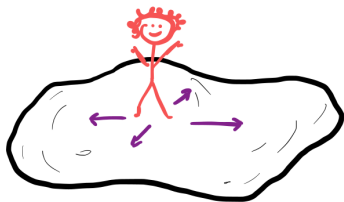
Question 3: moduli spaces

What does the solution space to an elliptic PDE look like?

Manifolds

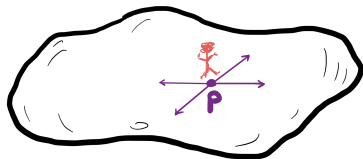
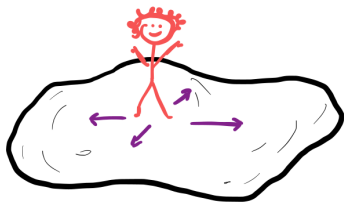


Manifolds



surface of a potato is a manifold: locally looks like a disk

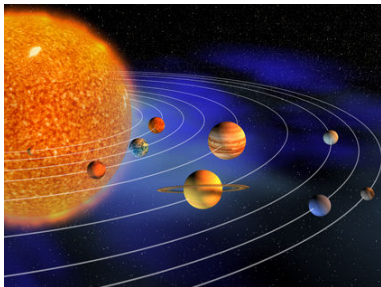
Manifolds



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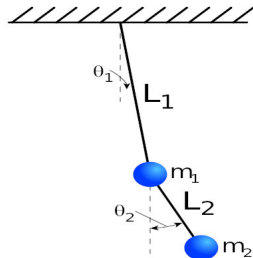
smooth manifold: second countable Hausdorff topological space M
 locally diffeomorphic to open ball in \mathbb{R}^n

Motivation: Hamiltonian mechanics



The solar system (simplified).

Source: <http://www.scienceclarified.com/photos/solar-system-2865.jpg>



A double pendulum.

Source: By JabberWok, CC BY-SA 3.0,
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Hamiltonian systems: from Newton's to Hamilton's equations

- system of particles moving with n degrees of freedom

$$q(t) = (q_1(t), \dots, q_n(t))$$

- forces are derived from a **potential** $V(q)$ by $F(q) = -\nabla V(q)$
- Newton's second law states $m_i \ddot{q}_j = -\frac{\partial V}{\partial q_j}$

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- Hamilton: consider momenta $p_j := m_j \dot{q}_j$
- total energy defines the Hamiltonian function

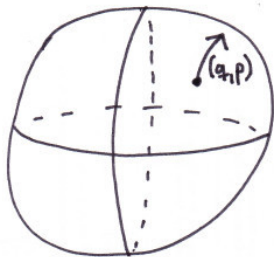
$$H: \mathbb{R}^{2n} \rightarrow \mathbb{R}, \quad (q, p) \mapsto \underbrace{\sum_{j=1}^n \frac{p_j^2}{2m_j}}_{\text{kinetic energy}} + \underbrace{V(q)}_{\text{potential forces}}$$

- Newton's equations become **Hamilton's equations**

$$\dot{q}_j = \frac{\partial H}{\partial p_j} \quad \text{and} \quad \dot{p}_j = -\frac{\partial H}{\partial q_j}, \quad \text{for } j = 1, \dots, n \quad (\text{H})$$

Hamilton's equations on a manifold: symplectic manifolds

- key insight: regard $(q(t), p(t))$ as trajectory in **phase space** $\mathbb{R}^{2n} = T^*\mathbb{R}^n$
- double pendulum: rigid arms mean $q(t) = (q_1(t), q_2(t)) \in \mathbb{T}^2$, phase space is cotangent bundle $T^*\mathbb{T}^2$
- for systems with constraints, treat (q, p) as **local coordinates** of a point moving in a manifold



Fact

A smooth $2n$ -dimensional manifold is **symplectic** iff it is covered by coordinate charts $(q_1, p_1, \dots, q_n, p_n)$ such that for all smooth $H: M \rightarrow \mathbb{R}$, all coordinate changes preserve the form of (H).

Hamilton's equation in symplectic manifolds

Definition

For (M, ω) symplectic, $H: \mathbb{R} \times M \rightarrow \mathbb{R}$ smooth, the **Hamiltonian vector field** X_{H_t} of H is defined by $\omega(X_{H_t}, \cdot) = -dH(t, \cdot)$.

Exercise

Solutions (q, p) of (H) are the integral curves of X_{H_t} .

Sample theorems I: periodic orbits of dynamical systems

Arnold conjecture

If M is a closed* symplectic manifold and $H: \mathbb{S}^1 \times M \rightarrow \mathbb{R}$ smooth and non-degenerate, then

$$\# \text{ 1-periodic orbits of } X_H \geq \sum_{i=1}^n b_i(M),$$

where $b_i(M) := \text{rk } H_i(M)$ is the i -th Betti number of M .

(Almost the) Conley conjecture

M is a closed symplectic manifold with e.g. $\pi_2(M) = 0$

$H: \mathbb{S}^1 \times M \rightarrow \mathbb{R}$ is smooth and non-degenerate,

then X_H has infinitely many simple orbits of integer period.

Sample theorems II: symplectic fillings

Definition

A **smooth filling** of a smooth manifold M is a compact manifold N with $\partial N \cong M$.

not always possible ($\mathbb{C}P^2$ has no smooth filling),
but well understood (bordism theory, 1960s)

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Definition

A **contact manifold** $(M^{2n-1}, \xi = \ker \alpha)$ is a smooth manifold M together with a choice of 1-form α s.t. $\alpha \wedge d\alpha^{n-1} \neq 0$.

Template definition

A **symplectic filling** of (M, ξ) is a compact symplectic manifold (W, ω) with $\partial W \cong (M, \xi)$.

Sample theorem II: symplectic fillings (cont.)

Template definition

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Definition

An **exact symplectic filling** of (M, ξ) is a compact symplectic manifold $(W, \omega = d\lambda)$ s.t. $\partial W \cong (M, \xi)$ and the vector field X induced by $\iota_X \omega = \lambda$ points outwards along ∂W .

Theorem (Zhou '20+'22)

If $n \geq 3$ and $n \neq 4$, $(\mathbb{R}P^{2n-1}, \xi_{std})$ has no exact symplectic filling.

Underlying paradigm: symplectic invariants

- Arnold, Conley conjecture: use Hamiltonian Floer homology
- (M, ω) symplectic \rightarrow homology groups $HF_*(M)$, generated by 1-periodic Hamiltonian orbits
- Arnold conjecture: bound $\#$ orbits via $\text{rk } HF_*(M)$
- Conley conjecture: pass to higher iterates
- Zhou's theorem: use more advanced invariant to exclude hypothetical filling (action-filtered positive symplectic homology)

Pseudo-holomorphic curves

Definition

An **almost complex structure** on a smooth manifold M is a collection of maps $J_p: T_pM \rightarrow T_pM$ with $J_p^2 = -\text{id}$, smoothly varying in p .

Theorem

Every symplectic manifold admits an almost complex structure.

intuition: J is an auxiliary object

Pseudo-holomorphic curves

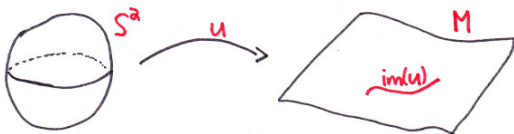
Definition

A **Riemann surface** is a smooth surface with a choice of almost complex structure.



Definition

A closed **pseudo-holomorphic curve** is a smooth map $u: (\Sigma, j) \rightarrow (M, J)$ with $J \circ du = du \circ j$, where (Σ, j) is a closed Riemann surface and (M, J) an almost complex manifold.



Moduli space of holomorphic curves

(M, ω) symplectic, almost complex structure J on M ,
genus $g \geq 0$ and homology class $A \in H_2(M)$
consider the **moduli space** of holomorphic curves

$$\mathcal{M}_g(A, J) := \{u: (\Sigma, j) \rightarrow (M, J) \mid u \text{ ps.-holo}; \Sigma \cong \Sigma_g, u_*[\Sigma] = A\} / \sim$$

Wishful thinking

$\mathcal{M}_g(A, J)$ is a compact smooth manifold (and finite-dimensional).

Understanding the moduli space of holomorphic curves

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- $u: (\Sigma, j) \rightarrow (M, J)$ is J -holomorphic iff $du + J \circ du \circ j = 0$
i.e. $\mathcal{M}_g(A, J)$ is the zero set of $\Phi: (u, J) \mapsto du + J \circ du \circ j$

Understanding the moduli space of holomorphic curves

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Finite-dimensional Implicit function theorem

$E \rightarrow B$ smooth vector bundle, $s: B \rightarrow E$ smooth section transverse to the zero section. Then $s^{-1}(0) \subset B$ is a smooth submanifold.

domain of Φ is $C^\infty(\Sigma, M) \times \mathcal{J}(M, \omega)$, where $\mathcal{J}(M, \omega)$ is the space of all compatible almost complex structures

Infinite-dimensional complications

$\mathcal{M}_g(A, J)$ is the zero set of $\Phi: C^\infty(\Sigma, M) \times \mathcal{J}(M, \omega) \rightarrow \dots$,
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- linearisation of section must have a bounded right inverse:
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- linearisation of section must have a bounded right inverse:
ok, $d\Phi$ is a **Fredholm operator**
- domain must be a **Banach manifold**:
but $C^\infty(\Sigma, M)$ is not complete!
- solution: extend Φ to a larger domain,
e.g. **Sobolev spaces** $W^{k,p}(\Sigma, M)$ for $kp > 2$
- **elliptic regularity**: extension has same zero set

Bad news: transversality and compactness

- $\mathcal{M}_g(A, J)$ is not compact, but can compactify
require compatible J (i.e. $\omega(\cdot, J\cdot)$ Riemannian metric)

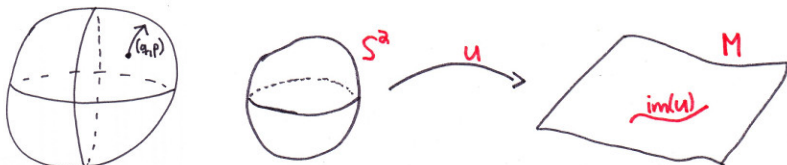
Bad news: transversality and compactness

- $\mathcal{M}_g(A, J)$ is not compact, but can compactify
require compatible J (i.e. $\omega(\cdot, J\cdot)$ Riemannian metric)
- transversality failure: for some J , $\mathcal{M}_g(A, J)$ is not a manifold
best case: holds for “generic” J
- more generally: transversality doesn't like symmetry
e.g. multiply covered curves (or external group action)

Theorem

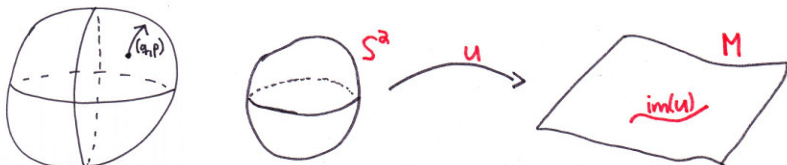
For “almost all” compatible J , $\mathcal{M}_g^*(A, J)$ is a compactifiable smooth manifold of dimension $(\frac{\dim M}{2} - 3)(2 - 2g) + 2\langle c_1(TM), A \rangle$.

Summary



- 1 Symplectic manifolds arise when describing mechanical systems.
- 2 Periodic orbits of Hamiltonian systems can be understood using symplectic invariants.
- 3 These invariants are defined using moduli spaces of pseudo-holomorphic curves.

Summary

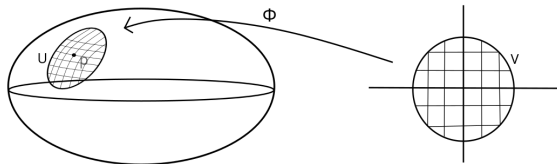


- 1 Symplectic manifolds arise when describing mechanical systems.
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Thanks for listening! Any questions?

Smooth manifolds

- manifold: second countable Hausdorff topological space M locally homeomorphic to open ball in \mathbb{R}^n
- every $p \in M$ has a coordinate chart: $p \in U \subset M$ open, homeomorphism $\phi: V \rightarrow U$ for $V \subset \mathbb{R}^n$ open ball
- smooth manifold: all coordinate transformations from overlapping charts are smooth
- boundary: looks like upper half of \mathbb{R}^n



Examples of smooth n -dimensional manifolds

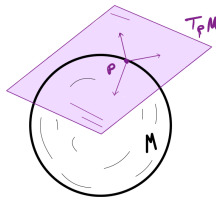
- $n = 0$: isolated points
- $n = 1$: \mathbb{R} , S^1
- $n = 2$: \mathbb{R}^2 , S^2 , T^2 , Σ_g for $g \geq 1$



- $n \geq 3$: complicated; classification for $n \geq 4$ impossible
- $n \geq 3$: \mathbb{R}^n , S^n , T^n , $\mathbb{R}P^n$, $\mathbb{C}P^n$,
 $\{[z_0 : z_1 : z_2 : z_3 : z_4] \in \mathbb{C}P^4 \mid z_0^5 + \dots + z_4^5 = 0\}$
 configuration spaces in physics and engineering

How to measure area on a 2-manifold?

- locally: integrate density function
- globally: use a differential 2-form
- each $p \in M$ has **tangent space** $T_p M$,
 n -dimensional \mathbb{R} -vector space
- 2-form $\omega = \{\omega_p: T_p M \times T_p M \rightarrow \mathbb{R}\}_{p \in M}$
 ω_p anti-symmetric bilinear,
smoothly varying with p
- area form**: each ω_p is non-degenerate
- symplectic 2-manifold**: M plus choice of area form



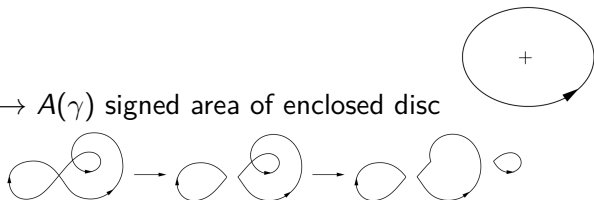
Symplectic manifolds

Definition

A **symplectic manifold** (M, ω) is a smooth manifold M together with a closed non-degenerate 2-form ω .

- equivalently: atlas of **Darboux charts** $(x_1, y_1, \dots, x_n, y_n)$ in which ω looks like $\omega_0 = \sum_{i=1}^n dx^i \wedge dy^i$
- geometrically: symp. structure = signed area of closed curves
- γ embedded closed curve in \mathbb{R}^2

→ $A(\gamma)$ signed area of enclosed disc



- γ any oriented closed piece-wise smooth curve:
decompose into closed embedded pieces

Symplectic manifolds (cont.)

- **standard symplectic structure** on \mathbb{R}^{2n} :
map $\gamma \rightarrow A(\gamma) = A(\gamma_1) + \cdots + A(\gamma_n)$,
where $\gamma = (\gamma_1, \dots, \gamma_n)$ any closed oriented curve
- symplectic structure on M is an atlas whose transition functions preserve signed area

Which manifolds are symplectic?

- no full answer known!
- necessary conditions
 - even dimension, orientable
 - \exists (compatible) almost complex structure
 - if compact: $H^{2i}(M) \neq 0$ for $0 < 2i < \dim(M)$
 - additional conditions on dimension 4

Example

Sphere \mathbb{S}^n is **not** symplectic for $n > 2$.

Proof sketch of Arnold conjecture

given (M, ω) closed*; $H: \mathbb{S}^1 \times M \rightarrow \mathbb{R}$ smooth non-degenerate

- $CF_k(M)$ is generated by 1-periodic orbits with index k
- in particular: #1-periodic orbits $\geq \sum_k \text{rk } HF_k(M)$
- Morse theory: $\sum_k \text{rk } H_k(M) \geq \sum_{i=0}^{2n} \text{rk } H_k(M)$

Theorem

For each k , there is an isomorphism $HF_k(M) \cong H_{2n-k}(M)$.

Details: Hamiltonian Floer homology

given: (M, ω) closed* symplectic manifold; $H: \mathbb{S}^1 \times M \rightarrow \mathbb{R}$
smooth, non-degenerate

- **Floer chain complex** $(CF_*(M, \omega), \partial)$,
Hamiltonian Floer homology $HF(M, \omega) = H_*(CF_*(M, \omega), \partial)$
- $CF_*(M)$ generated by 1-periodic orbits of X_H
- grading by Conley-Zehnder index
- differential counts finite energy **Floer cylinders**
connecting two 1-periodic orbits
- show: well-defined; independent of H